

# Lossless Compression Decoders for Bitstreams and Software Binaries Based on High-Level Synthesis

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**Abstract**—As the density of FPGAs has greatly improved over the past few years, the size of configuration bitstreams grows accordingly. Compression techniques can reduce memory size and save external memory bandwidth. To accelerate the configuration process and reduce software start-up time, four open-source lossless compression decoders developed using high-level synthesis techniques are presented. Moreover, in order to balance the objectives of compression ratio, decompression throughput, and hardware resource overhead, various improvements and optimizations are proposed. Full bitstreams and software binaries have been collected as a benchmark, and 33 partial bitstreams have also been developed and integrated into the benchmark. Evaluations of the synthesizable compression decoders are demonstrated on a Xilinx ZC706 board, showing higher decompression throughput than that of the existing lossless compression decoders using our benchmark. The proposed decoders can reduce software start-up time by up to 31.23% in embedded systems and 69.83% reduction of reconfiguration time for partial reconfigurable systems.

**Index Terms**—High-Level Synthesis, lossless compression, compression decoder, FPGA bitstream, software binary.

## I. INTRODUCTION

**D**URING the last decade, the progress in silicon technology has led to an enormous growth of resources on current SRAM-based Field Programmable Gate Arrays (FPGAs). As the amount of resources increases, the size of configuration memory needed to store the bitstreams grows accordingly. Bitstreams for high-end products from the leading FPGA vendors have broken through the 300 megabits barrier [1][2]. Storing the bitstreams in FPGA-based systems becomes a critical problem since it needs large external memory that could increase the overall system cost [3]-[7]. In high radiation

environments, continuing growth of bitstreams has become a dramatic problem as nonvolatile memory required to store the bitstreams must be radiation-hardened. Such memory has lower density and is much more expensive than conventional memory, resulting in very high system costs.

In addition to the hardware aspects, there is also an increase in the size of software binaries or executable programs that are executed in FPGA-based embedded systems. With the trend towards more complex software systems with respect to code size and the number of processors, the capacity of the external nonvolatile memory needed to store the software binaries grows accordingly. Furthermore, the required throughput for reading software binaries needs to improve in order to meet the limited start-up time of some systems [8].

To solve the above problems, bitstream and software binary compression techniques are developed to reduce the external memory usage and the required external memory bandwidth. There have been several approaches investigating the effectiveness of compressing bitstreams or software binaries. However, there are still three limitations of existing methods. First, there is no prior work that simultaneously addresses compression ratio, hardware resource overhead, and decompression throughput. Some compression techniques with good compression ratio and few hardware resources, have poor decompression throughput and hence are not competitive. Second, benchmarks are not available for full bitstreams, partial bitstreams, and software binaries, and do not represent the statistical characteristics for a wide range of applications. Third, there are substantial differences between implementation results and simulation results.

To address these challenges, four lossless compression decoders developed using High-Level Synthesis (HLS) techniques are presented. At the decompression level, various improvements and optimizations are applied to the compression decoders in order to balance the objectives of compression ratio, decompression throughput, and hardware resource overhead simultaneously. At the benchmark level, 28 full bitstreams and 25 software binaries have been collected. Thirty three partial bitstreams have been developed and integrated into the benchmark. Moreover, since no specific bitstream organizations and software binary data structures are required, these decoders are applicable to other modern FPGA

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devices and software binaries. Implementations of the proposed compression decoders can run at 200MHz. Evaluations of the synthesizable compression decoders are demonstrated on a Xilinx ZC706 board. The decompression throughput of the proposed compression decoders are superior to the existing lossless compression decoders on the benchmark by making use of different kinds of optimizations.

To summarize, the following contributions are made in this paper.

- 1) Four open-source lossless compression decoders are developed using HLS. Various improvements and optimizations are applied to these decoders in order to balance the objectives of compression ratio, decompression throughput, and hardware resource overhead. Implementations of the synthesizable lossless compression decoders can run at 200MHz.
- 2) A benchmark including full bitstreams, partial bitstreams, and software binaries is provided. Comparison results between the proposed compression decoders and the existing compression decoders on the benchmark are presented in respect of maximum frequency, as well as compression ratio, decompression throughput, and hardware resource overhead.
- 3) Evaluations of the synthesizable compression decoders are demonstrated on a Xilinx ZC706 board, showing higher decompression throughput than that of the existing compression decoders on the benchmark. Moreover, the proposed method can reduce software start-up time by up to 31.23% in embedded systems and 69.83% reduction of reconfiguration time for partial reconfigurable systems.

The rest of paper is organized as follows. Section II discusses related work. Section III gives overall design considerations. Section IV presents design and implementation of lossless compression decoders in detail. Experimental results and analysis are presented in Section V. Finally, Section VI concludes this paper.

## II. RELATED WORK

Existing compression techniques for bitstreams and software binaries can be classified into two categories based on whether they are device dependent during decompression.

### A. Device Dependent Approaches

Some methods require special hardware features during decompression, such as wildcard registers or configuration mechanism, which are provided only in certain FPGAs.

Wildcard registers allow configuration memory within the same row or column to be written simultaneously. Some approaches that take advantage of the characteristics targeting Xilinx XC6200 FPGAs are presented in [9][10]. By using these registers, faster configuration could be achieved. In addition, a subsequent approach [11] from the same authors takes advantage of these registers based on Run Length Encoding (RLE) for the same family of FPGAs. The use of “don’t cares” for bitstream compression has been proposed in [12][13].

However, the method requires specific information regarding the bitstream format and the internal structure of the FPGA. This information is confidential in modern FPGAs, preventing us from exploiting such techniques.

Some studies [13]-[16] investigate the ability to compress bitstreams using the configuration mechanism. These studies show that bitstreams can be compressed efficiently by utilizing inter-frame or intra-frame regularity. In addition, some researches [13][14] use frame reordering and runtime frame read-back to achieve better redundancy, which are combined with RLE, Huffman encoding, LZSS encoding or computing the XOR difference between frames. These complex compression technologies can produce excellent compression results. However, not only do these methods require the knowledge of the bitstream format and the internal structure of the FPGA, but they do not address the problem of decompression throughput and decompression hardware resource overhead.

### B. Device Independent Approaches

Altera incorporates a hardware compression decoder in products, such as Stratix II FPGAs [17]. This decompression feature allows FPGAs to receive a compressed configuration bitstream and decompress it at run-time, reducing storage requirements and configuration time. The Xilinx bitstream generation tool (BitGen) includes an option called “-g compress”, which uses multiple-frame write sequences to minimize the size of bitstreams. This option is appropriate for compression of full and partial bitstreams. Both Xilinx and Altera have built-in hardware compression decoders in the external configuration devices, such as the System ACE MPM [18], Platform Flash PROM [19], and Enhanced Configuration [20]. Using these devices, designers do not need the knowledge of the bitstream format and the internal structure of the FPGA. In fact, they can save the total solution cost including storage memory, board space, configuration speed, and source of supply. However, both Xilinx and Altera omit details on decompression throughput and hardware resource overhead.

There are also other approaches in the field of bitstream compression and decompression, which involve RLE methods, statistical methods, dictionary-based methods, bitmask-based methods, and other variations [3]-[7][21]-[26]. Since configuration bitstreams are processed as raw data, these proposed techniques are applicable to other SRAM-based FPGA device, and do not depend on specific features of the configuration mechanisms. A modified LZW dictionary-based compression method has been proposed in [3][4]. Although the decompression hardware is simple, the memory requirement is high. The work presented in [5][6] tends to be more exhaustive in terms of compression techniques. The authors discuss different bitstream compression techniques, and also compare their own compression methods with state-of-the-art software programs like GZIP applied to different bitstreams. But the decompression throughput is not competitive. The authors in [7] compare their compression techniques with previous methods, and the proposed compression decoder is designed carefully to

achieve less hardware resource overhead and higher frequency. Unfortunately, they do not address the decompression throughput. A detailed implementation of LZSS compression decoder has been shown in [21]. The decoder can decompress the compressed partial bitstreams at run-time, but the authors do not provide decompression throughput. The LZSS approach is also used to compress portable partial bitstreams in [22]. Reference [23] shows high compression efficiency of partial bitstreams using the XOR operation and RLE. However, BRAM is used to store partial bitstreams before configuration. Larger partial bitstream files need more BRAMs and hence this method is not suitable for large partial bitstream files. A wide range of compression algorithms have been evaluated in [24] based on eight benchmark circuits. Although the proposed compression decoders can run higher than 200MHz, the decompression throughput is compromised. The authors in [25] propose an optimized RLE method to compress partial bitstreams and use the corresponding compression decoder to accelerate configuration process. However, the throughput is low. A compression decoder based on LZ77 and bitmask schemes has been proposed in [26], but the hardware resource overhead is high and the decompression throughput is low. Not only do these methods consider the compression ratio of each algorithm, but also the frequency of compression decoders and hardware resource overhead.

The organization of software binaries are very different from FPGA bitstreams. Some methods are also appropriate for software binaries. The LZSS compression technique is utilized for software binaries minimization in [6]. Bitmask-based compression approaches are proposed to compress software binaries in [27][28]. However, the decompression throughput of the proposed decoders in this paper are superior to these lossless compression decoders.

Although compression techniques for bitstreams have been proposed, all the above compression decoders are designed using hand-written Register Transfer Level (RTL) descriptions. In this paper, four lossless compression decoders are developed using HLS. In order to balance the objectives of compression ratio, decompression throughput, and hardware resource overhead, various improvements and optimizations are applied to these decoders. Furthermore, an extended benchmark is provided, including full bitstreams, partial bitstreams, and software binaries.

### III. DESIGN CONSIDERATIONS

HLS is introduced in general, and then the process of compression and decompression are discussed.

#### A. High-Level Synthesis

High-level synthesis tools perform automated translation of high level language (e.g., C, C++, and SystemC) inputs to RTL implementations. HLS tools perform scheduling of operations to finite state machine states and binding of operations to functional units. They also generate I/O interfaces to connect with memory or other interface protocols. HLS tools include pragmas to guide optimization of area and performance. Efficient use of pragmas, together with code reorganizations to

make pragmas effective, are the key design and the optimization technique for HLS. In a word, HLS bridges hardware and software domains, which can improve both productivity for hardware designers and system performance for software designers [29][30].

In this paper, Xilinx Vivado HLS is used to develop and verify the compression decoders at the C-level. Multiple implementations based on the source code are created, using optimization directives and exploring the design space, which increase the possibility of finding an optimal implementation.

#### B. Process of Compression and Decompression

The goal of compression is to minimize the size of bitstreams and software binaries. The compression of bitstreams and software binaries is similar to data compression, taking advantage of regularity and repetitions existing in the data stream. The process of compression and decompression are shown in Fig. 1. The original software binaries or full and partial bitstreams are compressed at compilation-time as shown in Fig. 1(a). The compressed full bitstream is transferred to the off-chip decompressor, then the decompressed full bitstream is transmitted to the FPGA configuration memory through the configuration interface as shown in Fig. 1(b). For partial reconfiguration, the compressed partial bitstream stored in external memory is transferred to the on-chip decompressor, which is connected to the internal configuration port directly. Then the function implemented in the reconfigurable region is modified by the decompressed partial bitstream as shown in Fig. 1(c). In embedded systems, the CPU reads the compressed software binary stored in the external nonvolatile memory and transfers it to the external memory ①, such as DDR SDRAM. Then the compressed software binary is transmitted to the on-chip decompressor ②. Finally, the decompressed software binary is return to the external memory ③ as shown in Fig. 1(d).

There are two problems which must be resolved for the process of compression and decompression. First, an efficient compression encoder must be provided. The more efficient the compression encoder is, the more memory it can save. Second, since the decompression is performed at run-time, both decompression throughput and hardware resource overhead should be carefully considered. The resource overhead of the compression decoder should be as small as possible. The throughput of the decoder has to be higher than that of the configuration interface; otherwise the compression decoder will affect the configuration rates. In addition, any information loss in bitstreams or software binaries may generate undesired outputs, or even worse it may damage devices. Any lossless compression technique has to satisfy the following condition: the outputs of the decompressor must be the same as the original inputs of the compressor. Lossless compression techniques are well-studied with a lot of efficient methods. In this paper, four lossless compression techniques are selected, based on RLE [31], LZ77 [32], LZSS [33], and LZG [34]. The details of designs and implementations are presented in the following section.

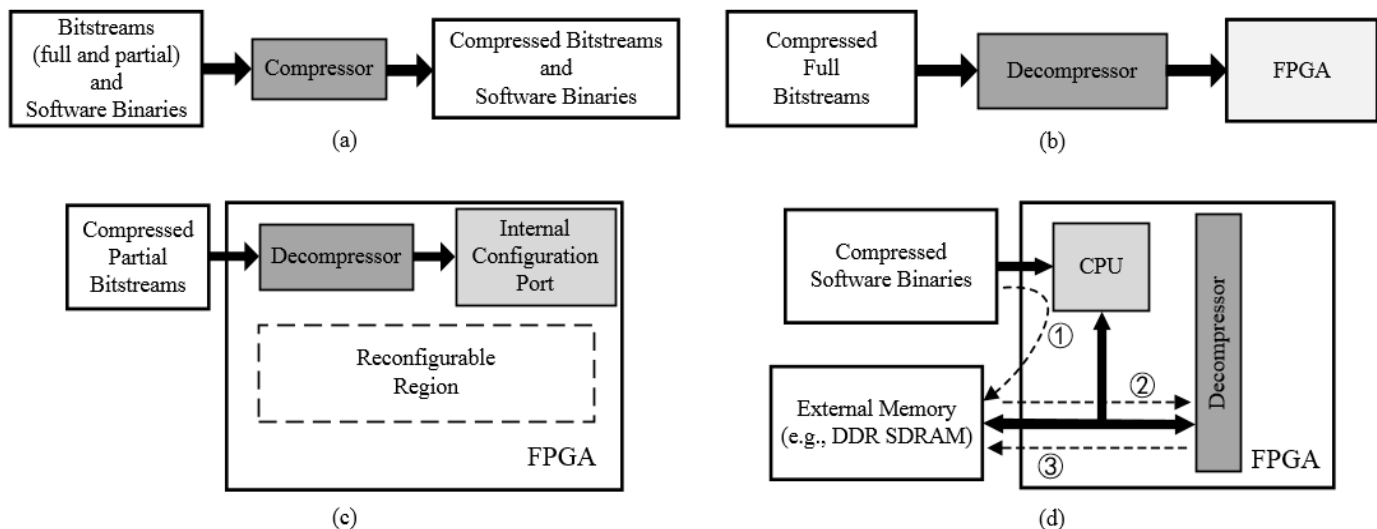


Fig. 1. The process of compression and decompression. (a) Compression stage (compilation-time, off-line). (b) Decompression stage of full bitstreams (run-time, off-chip). (c) Decompression stage of partial bitstreams (run-time, on-chip). (d) Decompression stage of software binaries (run-time, on-chip).

#### IV. DESIGN AND IMPLEMENTATION OF LOSSLESS COMPRESSION DECODERS

Design and implementation metrics are introduced in general. Then analysis of the benchmark and selections of reference codes are presented. Design flow and optimization methodology are discussed in more detail.

##### A. Design and Implementation Metrics

In this paper, compression techniques are compared and analyzed using the following metrics:

- 1) The compression ratio is widely used as a metric in [6][7]. It is defined as the ratio between the compressed data size and the original data size.

$$\text{Compression Ratio} = \frac{\text{Compressed Data Size}}{\text{Original Data Size}} \quad (1)$$

A smaller compression ratio means a better compression technique and saving more memory of external nonvolatile memory.

- 2) The decompression throughput is defined as the ratio between the decompressed data size (the same as the original data size) and the decompression time.

$$\text{Decompression Throughput} = \frac{\text{Decompressed Data Size}}{\text{Decompression Time}} \quad (2)$$

In order to speed up the hardware configuration and reduce software start-up time, higher decompression throughput is required.

- 3) The decompression efficiency is the ratio of the decompression throughput to the frequency and the data width.

$$\text{Decompression Efficiency} = \frac{\text{Decompression Throughput}}{\text{Frequency} \cdot \text{Data Width}} \quad (3)$$

To measure the efficiency of the decompression technique, the decompression efficiency is used as a metric.

- 4) Hardware Resource Overhead. Since decompression is performed at run-time, the hardware resource overhead of the compression decoder should be as small as possible.

Considering the above metrics, the required compression technology should have better compression ratio, higher decompression throughput, higher decompression efficiency, and less hardware resource overhead.

##### B. Analysis of the Benchmark

The following characteristics of the benchmark are shown in Fig. 2.

- 1) The probability of symbol (S) '0' is much higher than other symbols, especially for the partial bitstreams as shown in Fig. 2(a-c).
- 2) The probability of each symbol decreases with the increase of the symbol length (Ls) as shown in Fig. 2(a-c).
- 3) The average entropy of the 33 partial bitstreams is the lowest. The average entropy of the 25 software binaries is the highest as shown in Fig. 2(d).

Only one symbol consistently exhibits extremely high frequency for each category of the benchmark. There are more repetitive patterns in the 33 partial bitstreams and more random symbols in the 25 software binaries. These characteristics imply that partial bitstreams have a better compression ratio than full bitstreams and software binaries. Details of the compression ratio and the benchmark are presented in section V.

##### C. Reference Codes Selection

As discussed in section III, the compression technologies for bitstreams and software binaries have to be lossless. In the selection of reference codes, although only software compression decoders are the inputs to HLS, it is critical that

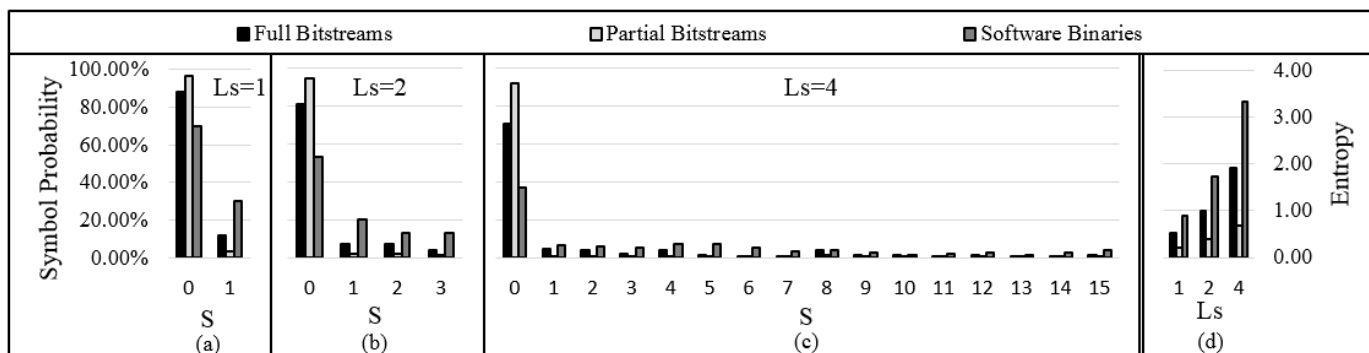


Fig. 2. Characteristics of the benchmark. (a)-(c) Symbol probability of symbol (S) value. (d) Entropy of symbol length (Ls).

software compression encoders are used consistently in order to generate the input data for the compression decoders. In addition, in order to perform HLS, the reference codes cover software compression decoders. Furthermore, the reference codes should not include embedded assembly or platform-dependent optimizations, which are not supported by Xilinx Vivado HLS.

To summarize, the following characteristics should be considered in the selection of reference codes.

- 1) Software implementations of both lossless compression and decompression methods are available.
- 2) The reference codes cover software compression decoders.
- 3) There are no embedded assembly or platform-dependent optimizations.

Based on the above characteristics, RLE [31], LZ77 [32], LZSS [33], and LZG [34] are selected.

In addition to the above considerations, RLE is simple and very useful for data that contains many repeating patterns. Three similar dictionary-based methods are selected for good compression ratio and simple decompression schemes. LZ77 and LZSS are widely used for bitstream compression [5][6][13][18][21][24]. Both methods can achieve good compression ratio, but the decompression throughput is not competitive. Compared with LZ77 and LZSS, the decompression method of LZG is simpler and faster with comparable compression ratio. Experimental results including the benchmark are presented in section V.

**RLE [31]:** If a data item  $D$  occurs  $N$  consecutive times in the input stream, replace the  $N$  occurrences with the single pair  $ND$ . Actually there is also a flag item  $F$  which is required during the RLE decompression. Thus, the compressed data stream is  $FND$ . RLE decompression is also straightforward. When a flag item  $F$  is read, the repetition count  $N$  and the actual data  $D$  are immediately read, and the data item  $D$  is written  $N$  times on the output stream.

**LZ77 [32]:** LZ77 is a dictionary-based text compression scheme. The scheme works by defining a sliding window or a fixed-size dictionary to hold data from an input stream, and then referring to the sliding window when compressing the remainder of the input stream. If a pattern in the input stream is already in the sliding window, this pattern is replaced with a length-distance pair. As compression progresses, the sliding

window is updated by shifting in more data from the input stream, subsequently forcing earlier entries out. Decompression is the inverse of the compression process. The same sliding window is used to hold uncompressed data. When a length-distance pair to the sliding window is encountered, the decompressor simply copies the specified number of data from the dictionary, shifts these data into the same sliding window, and then continues processing the rest of the compressed input stream.

**LZSS [33]:** LZSS is an efficient variant of LZ77. It holds the look-ahead buffer in a circular queue and holds the search buffer (the dictionary) in a binary search tree. Since the buffer size is 4096 bytes, the position can be encoded in 12 bits. The scheme also represents the match length in 4 bits, thus the position-length pair is just two bytes long. If the longest match is no more than two characters, then the scheme sends just one character without encoding, and continue the process with the next symbol. It also needs one extra bit each time to tell the decoder whether it is sending a position-length pair or an unencoded character.

**LZG [34]:** liblzg is a minimal implementation of an LZ77 class compression library. It implements an algorithm that is a variation of the LZ77 algorithm, with the primary focus of providing a very simple and fast decompression method. It contains four unique marker symbols, which are used to separate literal data from various forms of length-distance pair encodings.

#### D. Design Flow and Optimization Methodology

Fig. 3 shows a brief overview of the design flow and optimization methodology. The grey parts are the optimization methodology. The functional correctness of the compression decoder extracted from the reference code is verified with a C testbench. After all nonsynthesizable constructs are eliminated or converted for synthesizability, the initial hardware design of the compression decoder is generated by HLS with the default optimization. The initial design prepares for further optimizations. These optimizations will be discussed latter in more detail. In order to validate the optimized design, C/RTL cosimulation is performed within Vivado HLS. During C/RTL cosimulation, the same C testbench used in C simulation is reused and the synthesized function is replaced by the RTL

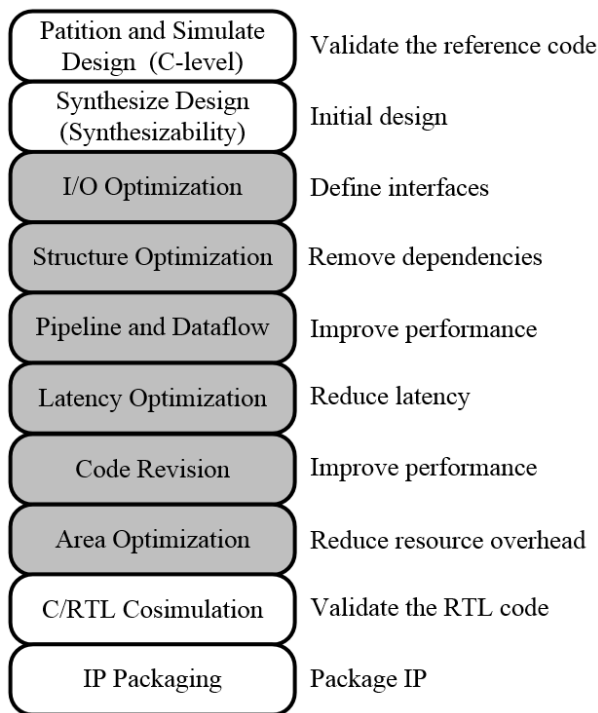


Fig. 3. Design flow and optimization methodology.

```

void hls_rle(hls::stream<unsigned char> &din, \
            hls::stream<unsigned char> &dout)
{
    //Inset the interface directives
    #pragma HLS INTERFACE axis port=dout
    #pragma HLS INTERFACE axis port=din
    ...
    RLE(din,dout)
}

```

Fig. 4. I/O optimization of the RLE decoder.

design. Once the C/RTL cosimulation is completed, the design is packaged as an IP. Detailed explanations of the design flow is presented in [35]. Optimizations are shown below.

### 1) I/O optimization

In C-level design, all input and output operations are performed in negligible time via a function call. In contrast, for an RTL design, these same input and output operations involves transferring data through I/O ports. Although Vivado HLS supports various I/O protocols, AXI4-Stream Interfaces without side-channels are used. These interfaces can be applied to any input or output arguments, and can achieve high performance. In addition, since the compression decoder accesses data in a streaming manner, these interfaces will not be the bottleneck. Furthermore, AXI4-Stream Interfaces are industrial standard interfaces and easy to use during the system design. Fig. 4 shows the I/O optimization of the RLE decoder. Other decoders are nearly the same. Fig. 5 shows the corresponding interfaces of the RLE decoder. The width of the I/O can be modified easily by changing the arguments.

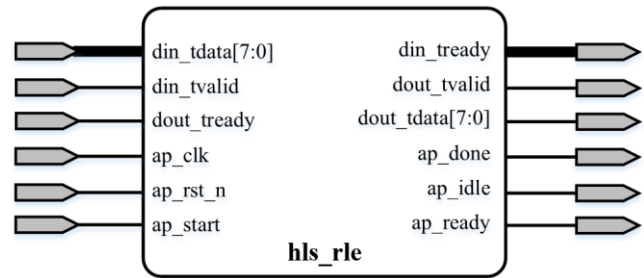


Fig. 5. Interfaces of the RLE decoder.

```

// shift register fuction before optimization
void shift_reg(int length, int offset)
{
    unsigned int i, tmp;

    //Define a shift register of type ap_shift_reg<type, depth>
    static ap_shift_reg<unsigned int, 2048> Sreg;
    L1:for (i=0; i<length; i++) {
        tmp = Sreg.read(offset-1);
        dout.write(tmp);
        Sreg.shift(tmp,0);
    }
}

```

Fig. 6. Shift register function before optimization.

### 2) Structure optimization

C/C++ code can contain dependencies that prevent a function or a loop from being pipelined. In these cases, code improvements are needed to remove the dependencies. A shift register function is synthesized as a slide window of the dictionary-based compression method. Fig. 6 shows the data dependency in the *L1* loop. There is the dependency between two shifting operations. Shifter writing *Sreg.shift(tmp,0)* cannot be executed until shifter reading *tmp = Sreg.read(offset-1)* has been executed. After structure optimization, Fig. 7 shows no data dependency in the *L2* and the *L3* loops. Even though data outputting *dout.write(tmp)*, shifter reading and writing *tmp1 = Sreg.shift(tmp,offset-2)*, as well as assignment *tmp=tmp1* appear serially in the code, these operations can be pipelined. Therefore, the data dependency between two operations can be removed by structure optimization. Although this optimization increases the hardware resource overhead, it can achieve higher performance.

### 3) Pipeline and dataflow optimizations

In order to improve the performance of the compression decoders, more and more concurrent and parallel operations are required. The pipeline optimization can be applied to functions and loops. The dataflow optimization can be applied at the task level that contains the functions and loops.

There is a tradeoff between area and performance when loops are pipelined. *L1* loops can be pipelined after code conversion shown in Fig. 8. But it can be seen that bad pipeline optimization may result in large hardware resource overhead and long latency. Thus, it might make no sense to improve the performance.

```
// optimized shift register fuction
void shift_reg(int length, int offset)
{
    unsigned int i, tmp, tmp1;

    //Define a shift register of type ap_shift_reg<type, depth>
    static ap_shift_reg<unsigned int, 2048> Sreg;

    //offset is more than zero
    tmp = Sreg.read(offset-1);
    if( offset>1) {
        L2:for( i=0; i<length; i++) {
            dout.write(tmp);
            tmp1 = Sreg.shift(tmp,offset-2);
            tmp=tmp1;
        }
    }
    else {
        L3:for( i=0; i<length; i++) {
            dout.write(tmp);
            Sreg.shift(tmp,0);
        }
    }
}
```

```
//bad shift register fuction
void shift_reg(int length, int offset)
{
    unsigned int i, tmp;

    //Define a shift register of type ap_shift_reg<type, depth>
    static ap_shift_reg<unsigned int, 2048> Sreg;

    //L1 loops can be pipelined
    #pragma HLS PIPELINE
    L1:for( i=0; i<=0x7FFFFFFF; i++) {
        if(i<length) {
            tmp = Sreg.read(offset-1);
            dout.write(tmp);
            Sreg.shift(tmp,0);
        }
    }
}
```

Fig. 8. Pipeline optimization of the shift register function.

Fig. 7. Structure optimization of the shift register function.

```
void hls_rle( hls::stream<unsigned char> &din, \
             hls::stream<unsigned char> &dout)
{
    //Inset the interface directives
    #pragma HLS INTERFACE axis port=dout
    #pragma HLS INTERFACE axis port=din

    ...
    RLE_0(din, dout);
    RLE_1(din, dout);
    RLE_2(din, dout);
}
```

```
void hls_rle( hls::stream<unsigned char> &din, \
             hls::stream<unsigned char> &dout)
{
    //Inset the interface directives
    #pragma HLS INTERFACE axis port=dout
    #pragma HLS INTERFACE axis port=din
    #pragma HLS DATAFLOW

    ...
    RLE_0(din, dout);
    RLE_1(din, dout);
    RLE_2(din, dout);
}
```

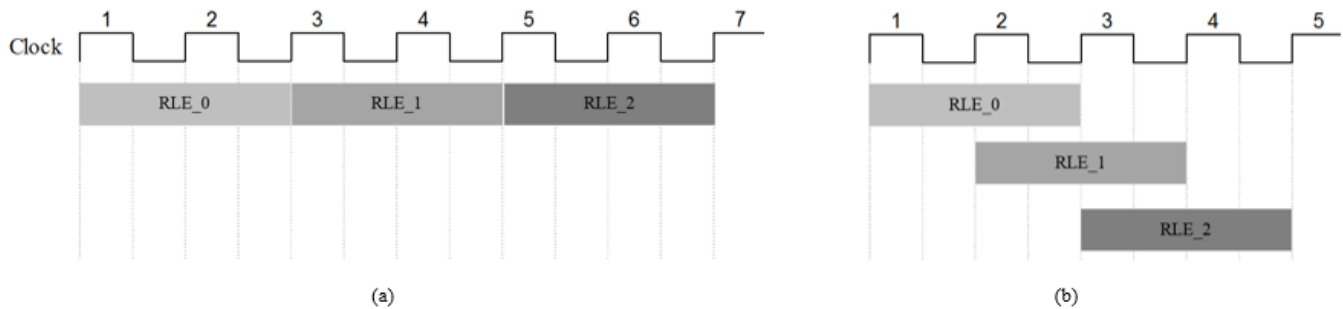


Fig. 9. Dataflow optimization of the RLE decoder. (a) Without dataflow optimization. (b) With dataflow optimization.

On the other hand, applying dataflow optimization can pipeline sequential tasks and improve performance. Compared with the RLE decoder shown in Fig. 4, we add another two tasks shown in Fig. 9 (a). The three tasks run serially and require 6 clock cycles without dataflow optimization shown in Fig. 9 (a). During dataflow optimization, Vivado HLS schedules each task to execute as soon as possible and allows executions of the three tasks to overlap with only 4 clock cycles, increasing the overall throughput of the design shown in Fig. 9 (b). Because the three tasks share the same interfaces, they cannot be executed concurrently within 2 clock cycles.

#### 4) Latency optimization

There is no need to apply latency optimization when the loops or function are pipelined. However, if the loops or functions are not pipelined shown in Fig. 7, the overall throughput will be limited by the latency, because the task does not start reading until the task has completed. In this case, the maximum latency is needed to be constrained.

#### 5) Code revision

In order to improve the decompression throughput further, the reference code revision is required. For example, when a data item occurs three consecutive times, RLE method

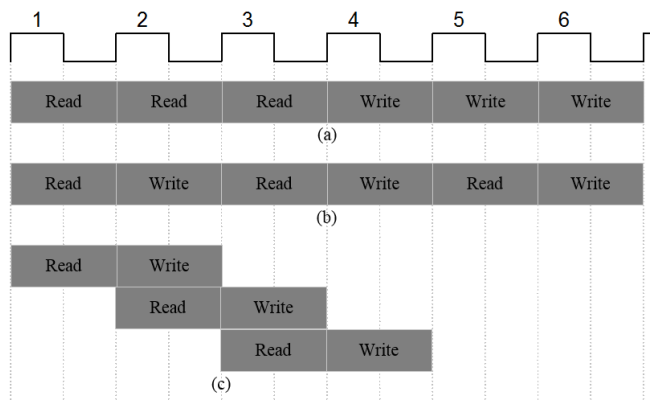


Fig. 10. Code revision of the RLE decoder. (a) RLE decompression process before code revision. (b) RLE decompression process after code revision. (c) Code revision with dataflow optimization.

compresses the input stream with three characteristics discussed in section IV-C. The corresponding RLE decompression process is shown in Fig. 10 (a). The decoder reads three times (flag item, repetition count, and actual data), and then the actual data are written three times on the output stream. The RLE encoder does not compress the input stream until the data item occurs more than three consecutive times after the code revision. Thus, this optimization does not affect the compression ratio. The RLE decoder alternates reading input stream and writing output stream presented in Fig. 10 (b). Combining with the dataflow optimization, the decompression throughput is improved, whereas the compression ratio is not affected by the code revision shown in Fig. 10 (c).

#### 6) Area optimization.

Different optimizations have different effects on the hardware resource overhead. In order to increase the throughput of the design, part of the codes are pipelined. Thus, this optimization increases the hardware resource overhead. Width improvement of I/O interfaces are also applied to these decoders. Wider I/O interfaces mean higher performance and larger hardware resource overhead. In order to achieve higher performance and less hardware resource overhead, arbitrary precision data types are used and the widths of variables can be arbitrary. In standard C/C++ data types, the widths of variables are 8, 16, 32 and so on. Thus, using the standard C/C++ data types results in unnecessary hardware resource overhead. Furthermore, it has a negative effect on the timing of the overall design. Compared with the shift register function shown in Fig. 6, the area optimization of the shift register function is illustrated in Fig. 11. As the depth of the shifter is 2048, the 11bit unsigned integer data type is used to reduce hardware resource overhead compared to using the 32bit signed integer data type for the variable *offset*.

## V. EXPERIMENTAL RESULTS AND ANALYSIS

A benchmark including full bitstreams, partial bitstreams, and software binaries is presented. Then the general evaluation system is introduced with four metrics. Finally, evaluations of the embedded system and the partial reconfigurable system are discussed.

```
#include "ap_int.h"

// shift register fuction before optimization
void shift_reg(int length, ap_uint<11> offset)
{
    unsigned int i, tmp;

    //Define a shift register of type ap_shift_reg<type, depth>
    static ap_shift_reg<unsigned int, 2048> Sreg;
    LL:for (i=0; i<length; i++) {
        tmp = Sreg.read(offset-1);
        dout.write(tmp);
        Sreg.shift(tmp,0);
    }
}
```

Fig. 11. Area optimization of the shift register function.

### A. Benchmark

In order to investigate different compression decoders, a suitable benchmark is required. The benchmark should include full bitstreams, partial bitstreams, and software binaries.

#### 1) Full bitstreams

Bitstreams that represent the statistical characteristics for a wide range of applications are collected. These applications are cryptography applications (DES and RC5), signal processing applications (FFT and FIR), system applications (SoC), and communication applications (Xbar and Net). Both Altera and Xilinx bitstreams are provided. These full bitstreams have a high logic utilization of the available resources. More details can be found in [5][36].

#### 2) Partial bitstreams

TABLE I summarizes the partial bitstream benchmark. The table lists the source of the modules, the register utilization, the LUT utilization, the slice distribution, and the bitstream size for different modules. These implementations are generated using the default configuration of place and route methodology, with no attempt to increase the structure regularity for partial bitstreams by manual optimizations. Bitstreams of Blank are automatically generated by the bitstream generation tool. Other modules are chosen from different applications:

- Signal processing applications include a float point adder or subtractor (Add/Sub), a coordinate rotational digital computer (CORDIC), a Discrete Cosine Transform module (DCT) [37], and a divider (Div).
- Cryptography applications contain an Advanced Encryption Standard module (AES) [38], an AES decryption module (AESD) [38], and a Data Encryption Standard module (DES) [39]. These modules are all from OpenCores.
- Communication applications include a cyclic redundancy check module (CRC) [40], a FIFO module, and a loopback module.

All partial bitstreams are generated by Xilinx Vivado 2015.4 with three different options. “Default” means the default option of bitstream generator. The “Xilinx Compression” option uses multiple-frame write sequences to minimize the size of



TABLE I  
PARTIAL BITSTREAM BENCHMARK

Module	source	Slice Utilization		Slice Distribution	Place and Route Methodology	Bitstream Size (Bytes)		
		Register	LUT			Default	Xilinx Compression	CRC per Frame
Add/Sub(fp)	Xilinx	12.45%	14.50%	29.13%	Auto	418,496	141,112	436,444
AES	OpenCores	17.61%	41.50%	66.75%			142,568	
AESI	OpenCores	41.84%	61.56%	98.50%			142,568	
Blank	Xilinx	0.00%	2.19%	5.13%			87,120	
CORDIC	Xilinx	9.00%	17.81%	27.63%			142,748	
CRC	OpenCores	1.56%	4.53%	6.38%			117,356	
DCT	OpenCores	13.08%	47.31%	63.13%			142,568	
DES	OpenCores	6.19%	12.47%	22.63%			132,316	
Div	Xilinx	14.08%	12.44%	34.25%			140,788	
FIFO	Xilinx	2.91%	4.84%	7.00%			116,956	
Loopback	By hand	1.05%	0.16%	2.50%			82,952	

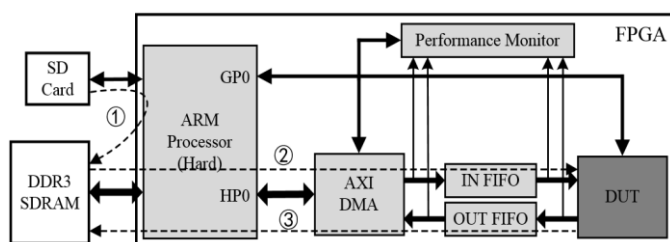


Fig. 12. Architecture of the evaluation system.

bitstreams. This is the same as the “-g compress” option in the previous Xilinx BitGen tool. It is device independent and appropriate for both full and partial bitstreams. Whether the slice distribution is high or low, the compressed size of the partial bitstreams is similar. The bitstream generator adds an extra CRC value after each frame by using the “CRC per frame” option. Thus, the size of bitstream is larger than that of the “default” option. In order to evaluate the influences of bitstream generation options on the compression technologies, the three types of partial bitstreams are used.

### 3) Software binaries

In order to evaluate the efficiency of compression technologies for software binaries in embedded systems, 25 software binaries are collected. These software binaries are Lightweight IP (lwIP) application examples, and can run on both MicroBlaze and ARM processor based systems with different cache size. The size of these software binaries varies from 300KB to 2MB. One of these software binaries is the initialization of the hard ARM processor. More detailed information about the software binaries can be found in [41].

## B. General Evaluation System

### 1) Evaluation system architecture

To evaluate the four metrics of compression techniques, the Xilinx ZC706 board is adopted as the evaluation system. Four compression decoders are developed with Xilinx Vivado HLS 2015.4. Logic synthesis and implementation of each design are performed with Xilinx Vivado 2015.4. Fig. 12 shows the architecture of the evaluation system, where the HP0 port,

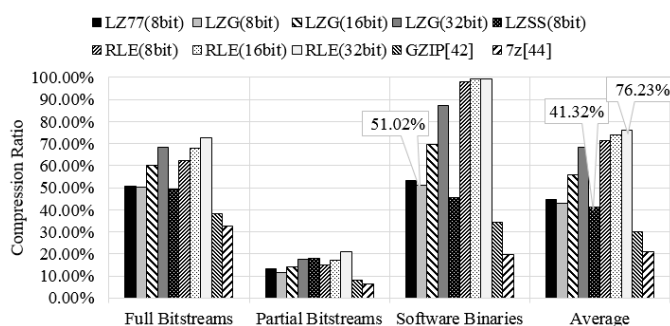


Fig. 13. Compression ratio of the benchmark.

the AXI DMA controller, IN FIFO, and OUT FIFO, as well as the Design Under Test (DUT) all run at 200MHz. The AXI DMA controller, the DUT, and the Performance Monitor are also connected to the GP0 port, which also runs at 200MHz. Each compression decoder is mapped to the DUT block. The compressed data and golden data are stored in the external SD card before system power-on. After the system is power-on, the ARM processor reads the data stored in the SD card and transfers the data to the external DDR3 SDRAM (1). Then the AXI DMA controller reads the compressed data from the DDR3 SDRAM and transmits it to the compression decoder (2), the decompressed data returns back to the DDR3 SDRAM after decompression (3). Finally, the Performance Monitor reports the result after checking the consistency between the decompressed data and the golden data.

### 2) Compression ratio

Fig. 13 shows the compression ratio of the benchmark. The first sub-graph shows the average compression ratio of 28 full bitstreams. The second and third sub-graphs present the average compression ratio of 33 partial bitstreams and 25 software binaries. The last sub-graph demonstrates the average compression ratio of the whole benchmark. Lower compression ratio means saving more memory and being more efficient. Thus, using these compression methods, 23.77%-58.68% (1-76.23% to 1-41.32%) memory can be saved for the benchmark. 8bit compression methods are more efficient than the 32bit compression methods. Because the partial bitstreams

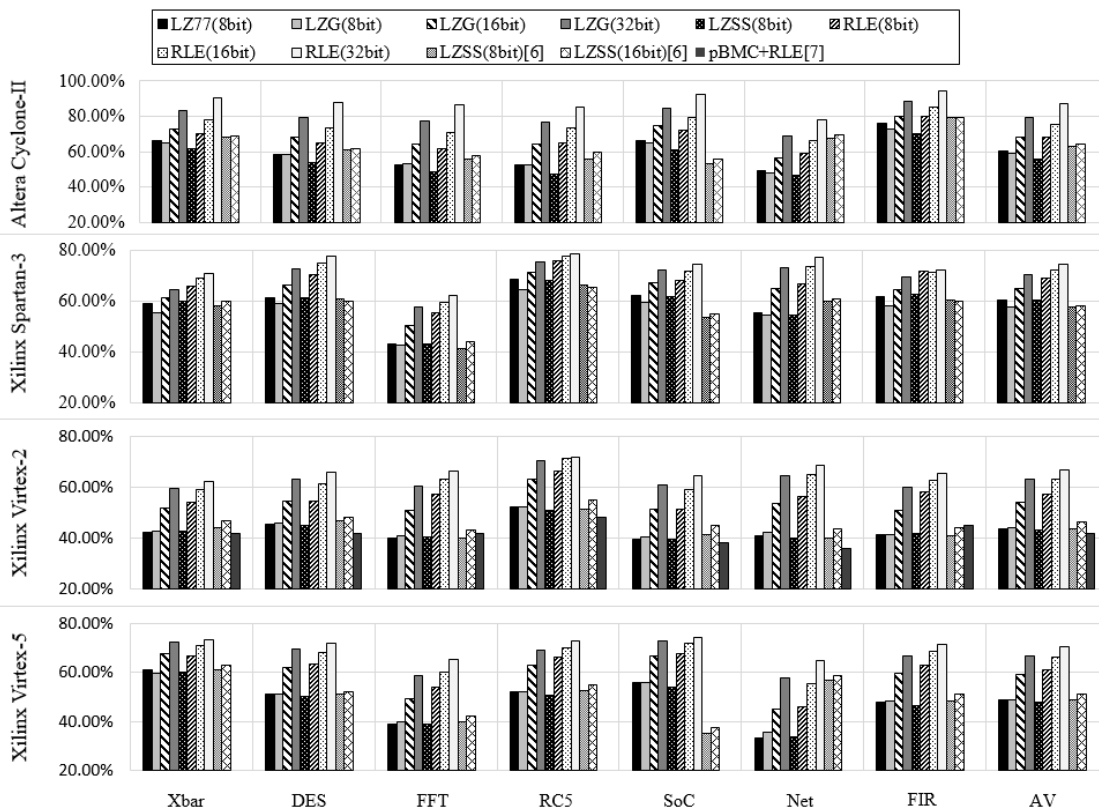


Fig. 14. Compression ratio of both Xilinx and Altera bitstreams.

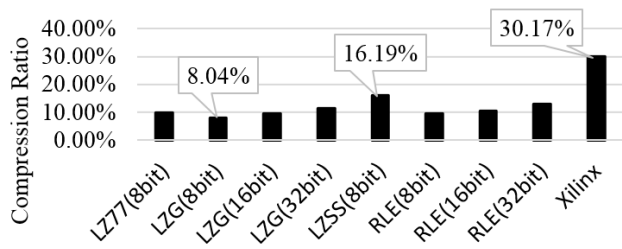


Fig. 15. Compression ratio of partial bitstreams.

have large amount of repetitive patterns, all the compression methods are applicable to the partial bitstreams and the compression ratio of the partial bitstreams is lower than 25%. Nevertheless, there are more random symbols in the software binaries, making RLE series unsuitable as they almost have no effect. LZG series is more efficient than RLE series, especially for software binaries. Compared with the state-of-the-art compression methods, such as GZIP (version 1.2.4) [42] and 7-zip (version 16.02) [44], the proposed compression technologies are less efficient, but the proposed decompressed methods have higher decompression throughput and less hardware resource overhead.

Compression ratios for 28 full bitstreams are presented in Fig. 14. Besides the bitstreams for different applications, we also compare the average ratio (AV) of all the bitstreams. Compared with the previous methods [6], the proposed compression technologies, LZ77(8bit), LZG(8bit), and LZSS(8bit) achieve better compression ratio on most of applications. Others are less efficient than the approaches [6]. The position-length pair

in LZSS(8bit) [6] is one byte long, while the position-length pair is two bytes long in this paper. More repetitive patterns can be matched with the longer position-length pair, thus the compression ratio of proposed LZSS(8bit) is better than that of LZSS(8bit) [6] except for SoC applications. However, more hardware resource are needed for the longer position-length pair. A bitmask-based method is designed to encode random bit changes and RLE is appropriate for large amount of repetitive patterns. pBMC+RLE [7] takes advantage of using bitmask and RLE to compress the Xilinx Virtex-2 bitstreams. As a result, pBMC+RLE [7] has a better compression ratio on some applications. Although some compression approaches have exhibited favorable compression ratio, no single compression method is efficient for the whole benchmark.

Furthermore, the proposed four compression techniques with different input and output widths outperform the Xilinx compression method by 14%-22% (30.17%-16.19 to 30.17%-8.04%) for the 11 “Default” partial bitstreams shown in Fig. 15. Because of many repetitive patterns in the partial bitstreams, the proposed four compression techniques are more efficient than Xilinx compression method for partial bitstreams.

### 3) Decompression throughput

The decompression throughput of the benchmark is illustrated in TABLE II. With the increasing data width of the compression decoder, the decompression throughput increases accordingly. Compared with LZG(8bit), LZG\_x1(32bit) with 32bit input/output achieves about 2.7 times higher decompression performance. On the other hand, applying dataflow optimization can pipeline sequential tasks and improve performance. Based on the design of LZG\_x1(32bit),

TABLE II  
IMPLEMENTATION RESULTS OF COMPRESSION DECODERS.

Type	LZ77 (8bit)	LZG (8bit)	LZG (16bit)	LZG_x1 (32bit)	LZG_x2 (32bit)	LZG_x3 (32bit)	LZSS (8bit)	RLE (8bit)	RLE (16bit)	RLE_x1 (32bit)	RLE_x2 (32bit)	RLE_x3 (32bit)
Register	399	93	153	189	342	487	311	33	57	105	141	177
LUT	1197	688	1252	2354	2608	2899	365	41	79	121	198	276
Compression Ratio	44.54%	43.08%	56.03%	68.13%			41.32%	71.51%	74.06%	76.23%		
Average Decompression Throughput (MB/s)	102.2	136.7	259.6	499.8	580.3	615.7	76.1	133.5	261.6	508.3	606.8	652.3
Decompression Efficiency (Normalized)	62.67%	83.85%	79.59%	76.62%	88.97%	94.39%	46.68%	81.89%	80.21%	77.93%	93.03%	100.00%

TABLE III  
COMPARISON OF DIFFERENT COMPRESSION DECODERS.

	LZG (8bit)	RLE_x3 (32bit)	LZG_x3 (32bit)	LZSS (8bit) [5][6]	LZSS (16bit) [5][6]	pBMC +RLE [7]	LZSS [21]	FDIC [24]	LZSS [24]	LZ77+ Bitmask [26]	Bitmask [27]	Bitmask [28]	GZIP [43]
Slice Usage	medium	low	high	low	low	low	low	low	low	high	low	N/A	highest
BRAM	0												10.5
Fmax(MHz)	205	381	205	198	200	195	75	395	277	109	130	326.8	165
Compression Ratio	good	not good	general	good	good	good	good	good	good	good	good	good	best
Average Decompression Throughput (MB/s)	136.7	652.2	615.7	198*	400*	N/A	N/A	424.6*	115.8*	211.5	N/A	N/A	495

\* This is the maximum decompression throughput.

LZG\_x3(32bit) adds extra two tasks and performs dataflow optimization. LZG\_x2(32bit) contains two tasks and also applies dataflow optimization. Although using this optimization method increases hardware resource overhead, LZG\_x3(32bit) achieves 23% higher decompression throughput than LZG\_x1(32bit). This optimization also applies to the RLE decoder.

#### 4) Hardware resource overhead

TABLE II lists the hardware resource overhead of each compression decoder. With the increasing data width of the compression decoder, the hardware resource overhead increase accordingly. Compared with RLE(8bit), RLE\_x1(32bit) with 32bit input/output costs about 3 times registers and LUTs. LZG\_x1(32bit) costs 2.03 times registers using area optimization method, but it costs 3.4 times LUTs compared with LZG(8bit). The shift register in LZG decoders are implemented by LUTs. According to the wider of the input and output, the resource overhead of the LUT increases more than that of the register.

#### 5) Decompression efficiency

The decompression efficiency of the compression decoders is shown in TABLE II. With the increasing data width of the compression decoder, the decompression efficiency decreases. However, decompression efficiency increases with the dataflow optimization. The decompression efficiency of the RLE\_x3(32bit) is superior to other decoders. The reasons behind these results come from the highest decompression throughput and dataflow optimization.

The implementation results of the three similar dictionary-based methods are shown in TABLE II. LZSS(8bit) has better average compression ratio than LZ77(8bit) and

LZG(8bit). Since the decompression method of LZG is simpler, LZG(8bit) achieves higher decompression throughput than LZSS(8bit) and LZ77(8bit). LZG(8bit) costs the medium hardware resource with the least number of registers and medium number of LUTs. Thus LZG(8bit) is more efficient than LZ77(8bit) and LZSS(8bit).

#### 6) Comparison and analysis

A comparison of different compression decoders is shown in TABLE III. Although the compression ratio of RLE\_x3(32bit) is worse than the existing compression decoders, RLE\_x3(32bit) can run at higher frequency and achieve higher decompression throughput with less hardware resource overhead. But RLE\_x3(32bit) is not appropriate for software binaries with large amount of random symbols. Nevertheless, LZG(8bit) is efficient for software binaries with medium hardware resource and good compression ratio.

In addition to the comparison given above, the decompression throughput of RLE\_x3(32bit) and LZG\_x3(32bit) is superior to the existing compression decoders on the benchmark. The reasons behind these results come from different kinds of optimizations.

#### 7) Impact of FIFO depth on the decompression throughput

In order to estimate the impact of FIFO depth on the decompression throughput, we perform measurements for different depth of the IN\_FIFO and OUT\_FIFO shown in Fig. 12. The depth of both IN\_FIFO and OUT\_FIFO varies from 16 to 512. Experimental results show that FIFO depth has little impact (less than 2%) on the performance of the DMA controller. However, the FIFO depth does not have impact on the decompression throughput. Larger FIFOs cannot achieve an improvement in decompression throughput.

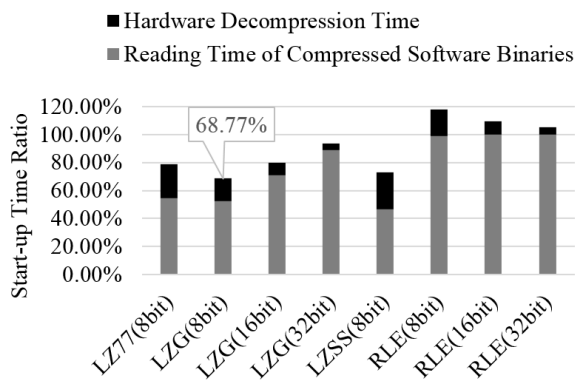


Fig. 16. Start-up time ratio of different compression decoders.

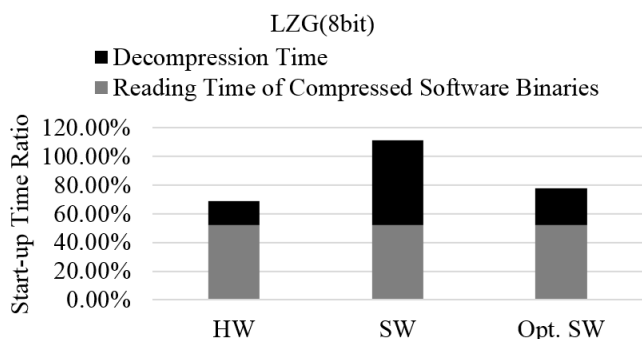


Fig. 17. Comparison of start-up time ratio between hardware and software.

### C. Embedded System

In order to evaluate the start-up time of the embedded system, the same architecture shown in Fig. 12 is used. The SD card controller runs at 50MHz with the maximum throughput of 25MB/s. The ARM processor runs at 666.66MHz and has a 32bit timer. The timer runs at 333.33MHz and is used to measure the start-up time. The compressed software binaries are stored in the external SD card before system power-on. In this system, the software binaries are so large that they have to run in the DDR3 SDRAM. The start-up time ratio is shown below.

$$Start-up\ Time\ Ratio = \frac{Reading\ Time + Decompression\ Time}{Original\ Start-up\ Time} \quad (4)$$

The original start-up time only includes reading uncompressed software binaries from the SD card and writing them to the DDR3 SDRAM. However, when using compression methods illustrated in Fig. 12, the start-up time not only contains the reading compressed software binaries from the SD card ①, but also includes the decompression time between the DDR3 SDRAM and the compression decoder②③. The reading time of the compressed/uncompressed software binaries is linear to the size of compressed/uncompressed software binaries. The boot loader runs on the on-chip memory with instruction cache and data cache enable. The decompression time not only contains the communication time between the DDR3 SDRAM and the compression decoder, but also includes the initialization of the DMA. Fig. 16 presents the average start-up time ratio (4) for different compression

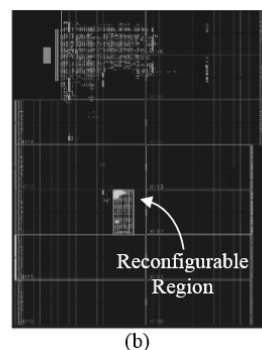
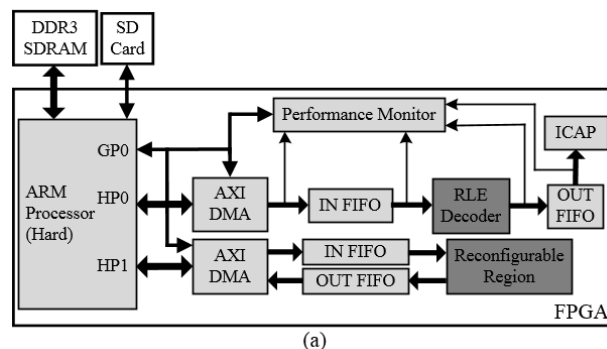


Fig. 18. (a) Architecture of the partial reconfigurable system. (b) FPGA floorplan.

decoders over the 25 software binaries. As the decompression throughput of the hardware compression decoders is higher than the maximum throughput of the SD card controller, the hardware decompression time is less than 25% of the original start-up time. Because of the compression of the software binaries, the reading time of the compressed software binaries is less than that of the original time. However, since the RLE compression methods are not efficient for software binaries, the total start-up time is more than original start-up time. The results shown in Fig. 16 reveal that LZG(8bit) is the best method to reduce the software start-up time. Because LZG(8bit) has good compression ratio and high decompression throughput, it can reduce 31.23% (1-68.77%) original start-up time and save 48.98% (1-51.02%) external memory.

In the evaluation system shown in Fig. 12, the compressed software binaries can also be decompressed by the software compression decoder running on the hard ARM processor. Fig. 17 illustrates the comparison of the average start-up time ratio between the hardware LZG(8bit) decoder and the software LZG(8bit) decoder for the 25 software binaries. Compared with the default software (SW) compression decoder, the optimized software (Opt. SW) compression decoder can reduce about 30% start-up time. However, hardware (HW) compression decoder also can achieve speed-up compared with the optimized software compression decoder.

### D. Partial Reconfigurable System

Fig. 18 presents the architecture of the partial reconfigurable system and the FPGA floorplan. Compared with the architecture of the general evaluation system shown in Fig. 12,

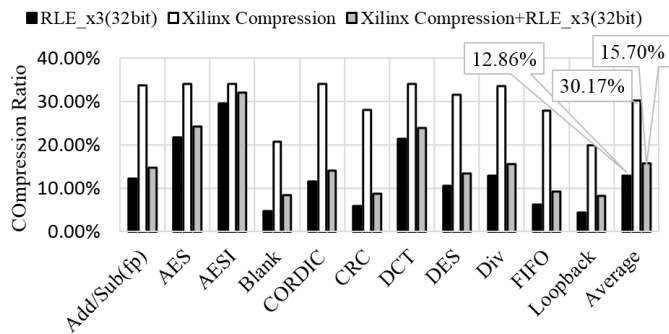


Fig. 19. Compression ratio of partial bitstreams.

the partial reconfigurable system adds another HP port and includes a reconfigurable region. The RLE\_x3(32bit) decoder is applied to the partial reconfigurable system because of the highest decompression throughput and less hardware resource overhead. The Internal Configuration Access Port (ICAP) runs at 100MHz. Overclocking of the ICAP is not recommended by the device vendor. To run safely, the speed limit of the ICAP is 100MHz. Therefore, the maximum throughput of the ICAP is 400MB/s with 32bit mode. As discussed in section V-B, the FIFO depth does not have impact on the decompression throughput. The RLE decoder runs at 142.8MHz and the maximum throughput of the RLE decoder is theoretically higher than 400MB/s. Thus, the performance of the ICAP is not affected by the RLE decoder and FIFO depth. Fig. 19 shows the compression ratio of partial bitstreams. The average compression ratio of the RLE\_x3(32bit) for the “Default” partial bitstreams is 12.86% and an 87.14% (1-12.86%) memory saving is achieved. At the same time, 86% memory bandwidth can be saved. Combining with the “Xilinx Compression” method and RLE\_x3(32bit), not only can 84.3% (1-15.7%) memory and 83% memory bandwidth be saved, but also 69.83% (1-30.17%) reconfiguration time can be reduced by using multiple-frame write sequences.

## VI. CONCLUSION

Compression techniques for bitstreams and software binaries have been extensively studied, but the existing compression decoders are designed using hand-written RTL descriptions and provide low decompression throughput. In this paper, four lossless compression decoders are developed using HLS. A benchmark including 28 full bitstreams, 33 partial bitstreams, and 25 software binaries is provided. Various improvements and optimizations are applied to the compression decoders in order to balance the objectives of compression ratio, decompression throughput, and hardware resource overhead simultaneously. Evaluations of the synthesizable compression decoders are demonstrated on a Xilinx ZC706 board running at 200MHz, showing higher decompression throughput than that of the existing compression decoders on the benchmark. Moreover, the proposed decoders LZG(8bit) can reduce software start-up time by up to 31.23% in embedded systems, and RLE(32bit) can reduce 69.83% reduction of the reconfiguration time for partial reconfigurable systems.

In addition, since no specific bitstream organizations or data structures are required, LZG(8bit) is applicable to other full bitstreams and software binaries. RLE(32bit) is efficient for partial bitstreams with low hardware resource usage and high decompression throughput. Although the proposed design method was demonstrated on a Xilinx ZYNQ FPGA, it can be applied to other FPGAs. The synthesizable lossless compression decoders and the benchmark can be download from the website [45].

Currently, we are exploring the combination of these compression decoders for a wide range of applications. Moreover, we plan to include error checking and error reporting logic within the compression decoders to improve reliability.

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